

SPEED MONITORING  
INCL. IMPULSE TRANSDUCER

# SWE

# 92.045 336.xxx



## APPLICATION

The SWE electronic speed monitor is used for underspeed monitoring, slip monitoring and standstill monitoring, especially in harsh "on-site operation". The opto-electronic pulse transducer, the speed evaluation relay and the power supply unit are combined into a single unit in the compact device.

This compact design eliminates the need for connecting cables between the encoder and evaluation relay, which are prone to interference in conventional electronic speed monitoring systems. This ensures interference-free signal transmission even over extremely long distances.

Only the supply voltage and the cables for the potential-free relay contact output are connected to the SWE.

The Kiepe electronic speed monitor type SWE conforms to the Low Voltage Directive 2014/35/EU and EMC Directive 2014/30/EU.

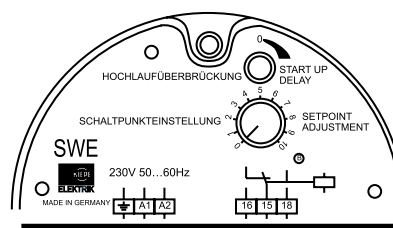
### Note:

The SWE may only be used in control circuits.

## FUNCTION

The device has a separate connection chamber in which the connection terminals, the potentiometers for setting the switching points and the start-up delay as well as the LED for the operating display are located. The time for the start up delay can be set from 0.5 to 15 seconds.

If the drive speed exceeds the pre-set operating speed, the relay is energized and the LED is lit. If the drive speed falls below the pre-set operating speed, the relay drops. The LED is extinguished.



## TECHNICAL DATA

Designation	Under-Speed Monitoring with Pulse Transducer Type SWE
Complies with	EN 50178 EN 61000-6-2 EN 61000-6-3
Suited for	Control circuits in accordance with DIN EN 60204-1
<b>Mechanics</b>	
Enclosure	Aluminum
Finish	PU 2K -paint, yellow (RAL 1004)
Mounting	4 x M6
Range of set point adjustment	see selection table
Weight	1.4 kg
<b>Electrical system</b>	
Supply voltages	AC 230 V $\pm 10\%$ , 50 ... 60 Hz
Relay output (Ag, flash plated)	1 change-over contact
Short circuit capacity	AC 230 V / 2 A (ohm resistive load) AC 230 V / 1 A ( $\cos \varphi = 0.4$ )
Switch point hysteresis (max.) of switch-off to switch-on speed	20 %
Switch point deviation	< 2 %
Output relay's operate time after switching on the actuating voltage	200 ms
Run-up bypass	0.5 ... 15 sec, adjustable
Cable entry (included in scope of supply)	2 x M25 x 1,5, (1x PA screwed cable gland: sealing area $\varnothing 9$ mm to $\varnothing 17$ mm; 1x dummy screw)
Connection cross section (max.)	2.5mm <sup>2</sup>
Protective conductor connection	Protection class I / Protective earthing
<b>Ambient conditions in accordance with DIN EN 60947-5-5</b>	
Permissible ambient temperature	-20 °C ... +70 °C
Protection rating (EN 60529)	IP 65






## SELECTION TABLE

Type	Number of Imp. / Rev.	Range of set point adjustment [rpm]	Cut-out delay sec.	Ordering Code
SWE 001 -2S	1	40 – 600	2.5 – 1.1	92.045 336.114
SWE 005 -2S	5	8 – 120	2.5 – 1.1	92.045 336.113
SWE 010 -2S	10	4 – 60	2.5 – 1.1	92.045 336.112
SWE 025 -2S	25	1.6 – 24	2.5 – 1.1	92.045 336.111

### Equipment options

SWE for AC 110 V, 50–60 Hz on request

## SPARE PARTS AND ACCESSORIES

Screwed cable gland, PA, M25 x 1,5; sealing area Ø 9mm to Ø 17mm		113.51.00.20.10
Screw plug, PA, M25 x 1,5		113.43.87.20.01
Circuit board (assembled), AC 230 V, 50 – 60 Hz		93.056 396. 001
Circuit board (assembled), AC 110 V, 50 – 60 Hz		93.056 396.002
Coupling K1 (curved-tooth gear)	for -2 S 	94.040 535.001
Coupling K7 (rubber bellow)	for -2 S 	94.040 535.004
Flange F1		96.038 986.003
Flange F2		96.038 986.004
Fixing Foot F4		96.038 986.002
Belt Drive B, Alu (S), without Roller		92.038 800.001
Plastic roller K		96.038 993.001
Rubber roller G		96.038 993.002
Hinge Pedestal GB		93.041 190.001

**Complete device assemblies consisting of SWE and accessories on request**

## MOUNTING

The SWE electronic speed monitors are supplied ready for operation.

Speed monitoring devices type SWE are attached to the substructure of the monitored machine using 4 M6 screws each. This is done using flange (F1, F2) or fixing foot F4. The connection to the rotating shaft is made using couplings (K1, K7). When the speed is taken directly from the belt, the SWE is attached to the belt drive B. The belt drive is pressed against the cleaned side of the belt using a hinge pedestal GB.

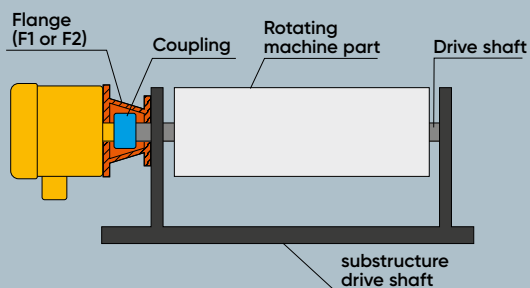
The electrical connection is made when the device is open via the cable gland included in the scope of delivery directly to the accessible connection terminals.

### Note:

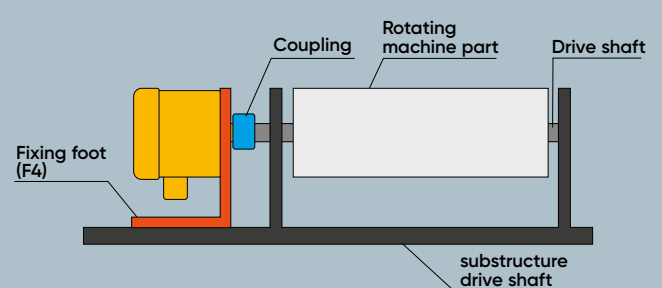
When using the belt drive B, make sure that the belt load cannot damage the SWE. With direct connection using fasteners, care must be taken to ensure that the SWE can resonate with the rotating part of the machine. (See mounting drawing)

## MOUNTING DRAWING

### Mounting directly on shaft

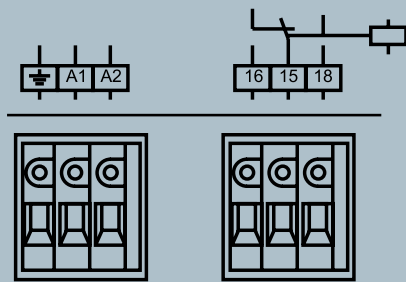


### Mounting on substructure

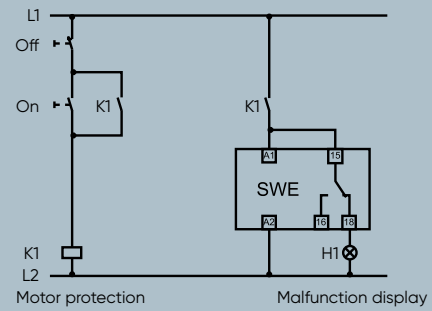


## CONNECTION DRAWING

### Connection

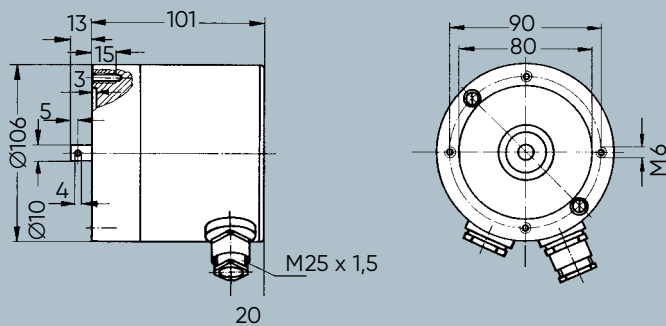


### Circuit example

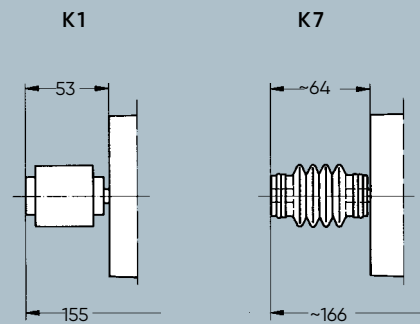


## DIMENSIONS

SWE

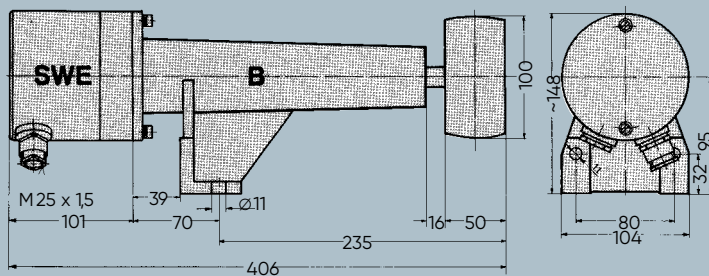


## Coupling



**SWEB**

SWE with belt drive B and roller G or K



### Mounting on upper belt

### Mounting on lower belt

